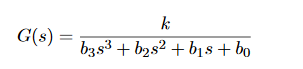
**Presentado por:**

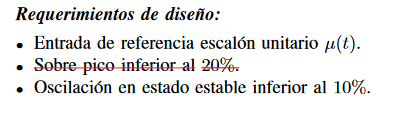
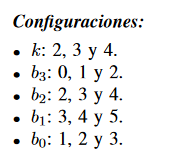
* Camila Lozano Jiménez - código 20201020161.
* Juan Felipe Rodríguez Galindo - código 20181020158.

**Enunciado:**

**VI. CONTROL CON NEURONAL NARMA-L2**

Implementar un sistema de control neuronal NARMA-L2 para una planta con la siguiente función de transferencia:





***Configuraciones:***

K = B = 3

b3 = C = 2

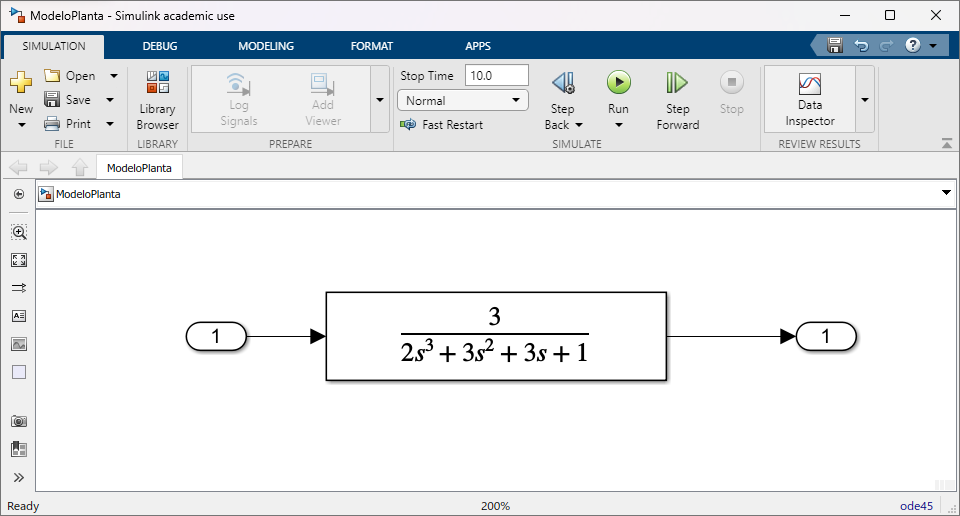
B2 = B = 3

b1 = A = 3

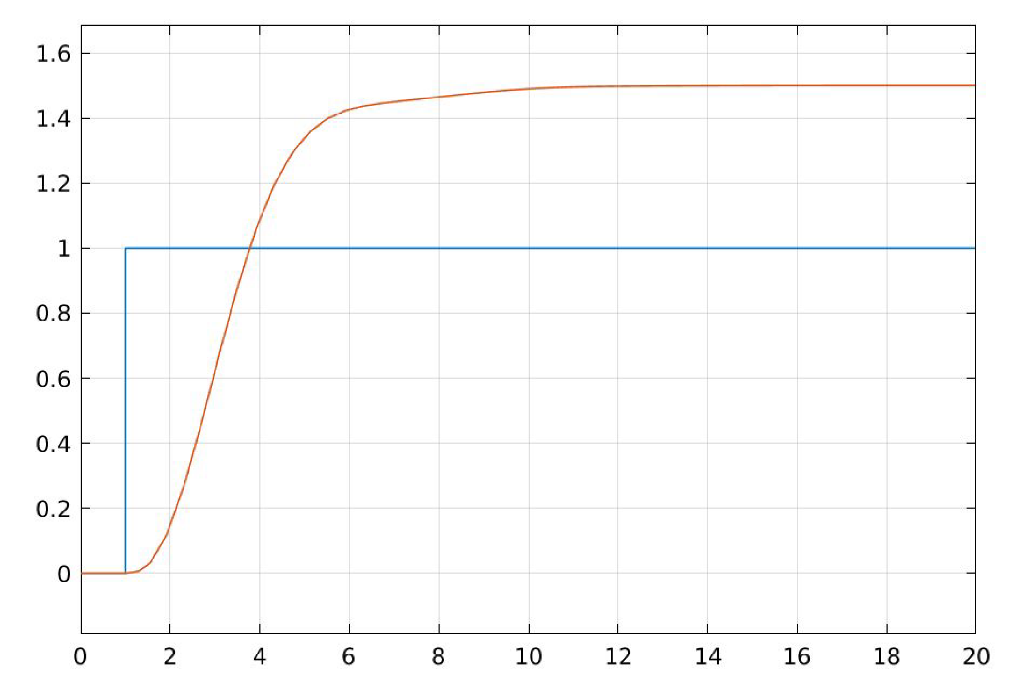
b0 = A = 1

**Desarrollo**

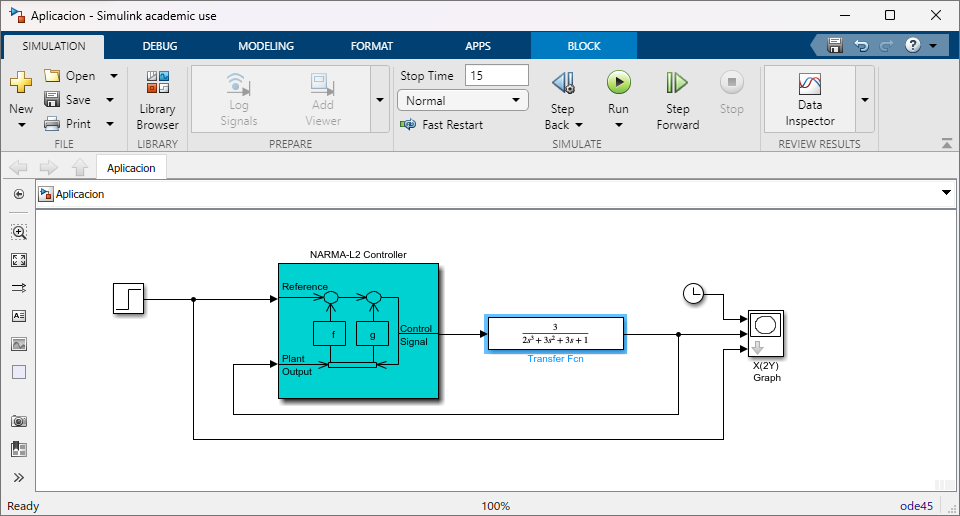
Modelo planta:



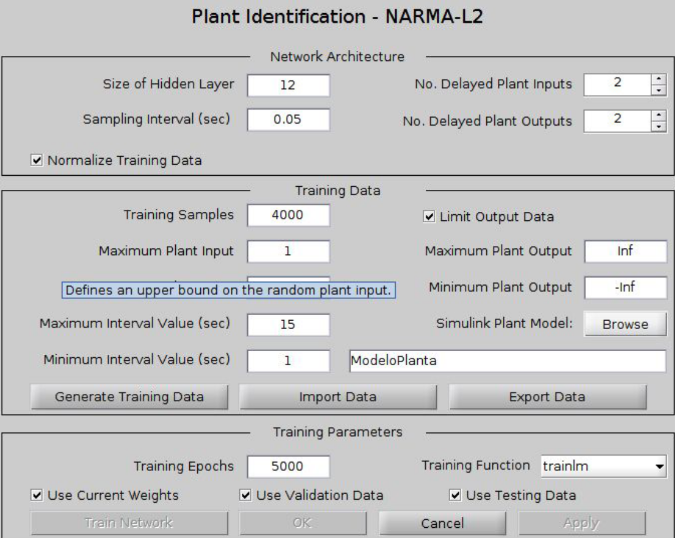
Con el cual podemos ver el comportamiento del sistema, el cual es:

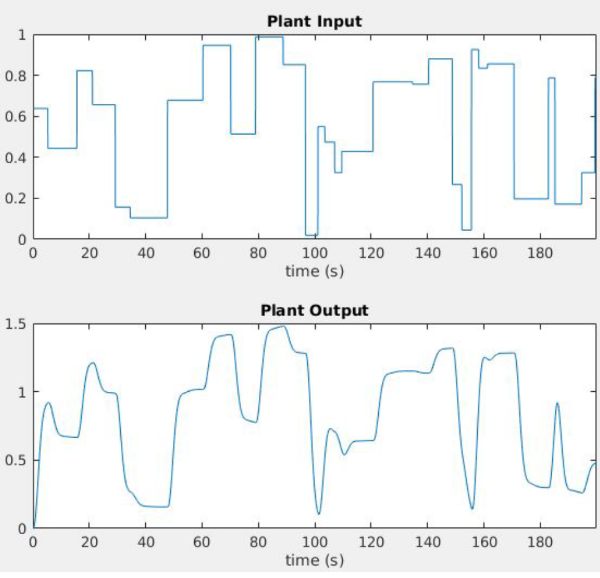


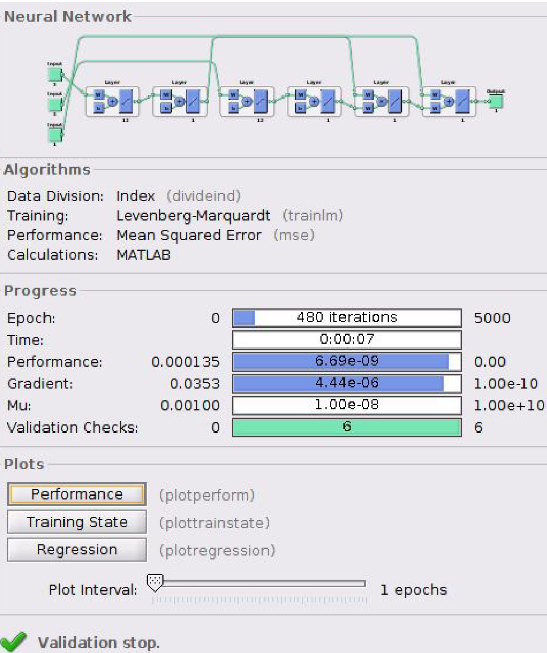
Creamos el controlador NARMA-L2

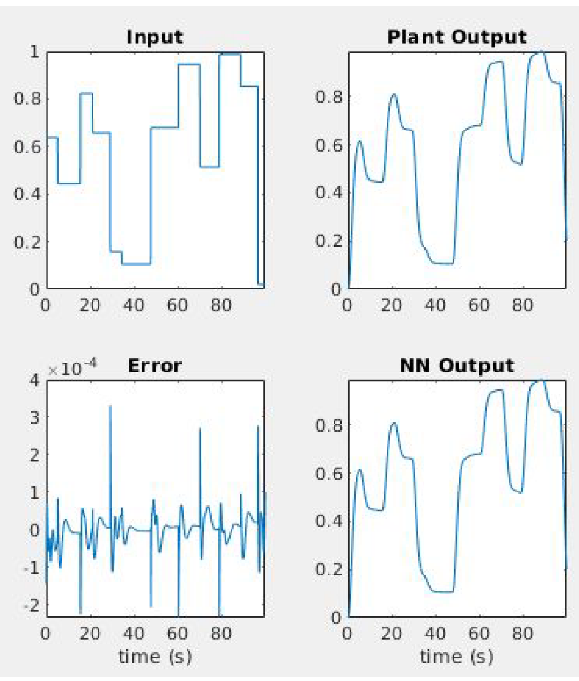


Configuración:





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Requerimientos:

